

Group Theory

Problem Set 9

December 4, 2001

Note: Problems marked with an asterisk are for Rapid Feedback.

- 1.* Consider the group $O(n)$, the elements of which preserve the Euclidean length in n dimensions:

$$x_1'^2 + x_2'^2 + \cdots + x_n'^2 = x_1^2 + x_2^2 + \cdots + x_n^2.$$

Show that these transformations have $\frac{1}{2}n(n-1)$ free parameters.

2. The condition that the Euclidean length is preserved in two dimensions, $x'^2 + y'^2 = x^2 + y^2$, was shown in lectures to require that

$$a_{11}^2 + a_{21}^2 = 1, \quad a_{11}a_{12} + a_{21}a_{22} = 0, \quad a_{12}^2 + a_{22}^2 = 1.$$

Show that these requirements imply that

$$(a_{11}a_{22} - a_{12}a_{21})^2 = 1.$$

3. Rotations in two dimensions can be parametrized by

$$R(\varphi) = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix}.$$

Show that

$$R(\varphi_1 + \varphi_2) = R(\varphi_1)R(\varphi_2)$$

and, hence, deduce that this group is Abelian.

- 4.* We showed in lectures that a rotation $R(\varphi)$ by an angle φ in two dimensions can be written as

$$R(\varphi) = e^{\varphi X},$$

where

$$X = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}.$$

Verify that

$$e^{\varphi X} = I \cos \varphi + X \sin \varphi,$$

where I is the two-dimensional unit matrix. This shows that $e^{\varphi X}$ is the rotation matrix in two dimensions.

5.* Consider the two-parameter group

$$x' = ax + b$$

Determine the infinitesimal operators of this group.

6.* Consider the group $C_{\infty v}$ which contains, in addition to all two-dimensional rotations, a reflection plane, denoted by σ_v in, say, the x - z plane. Is this group Abelian? What are the equivalence classes of this group?

Hint: Denoting reflection in the x - z plane by S , show that $SR(\varphi)S^{-1} = R(-\varphi)$.

7. By extending the procedure used in lectures for $SO(3)$, show that the infinitesimal generators of $SO(4)$, the group of proper rotations in four dimensions which leave the quantity $x^2 + y^2 + z^2 + w^2$ invariant, are

$$\begin{aligned} A_1 &= z \frac{\partial}{\partial y} - y \frac{\partial}{\partial z}, & A_2 &= x \frac{\partial}{\partial z} - z \frac{\partial}{\partial x}, & A_3 &= y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y} \\ B_1 &= x \frac{\partial}{\partial w} - w \frac{\partial}{\partial x}, & B_2 &= y \frac{\partial}{\partial w} - w \frac{\partial}{\partial y}, & B_3 &= z \frac{\partial}{\partial w} - w \frac{\partial}{\partial z} \end{aligned}$$

8. Show that the commutators of the generators obtained in Problem 7 are

$$[A_i, A_j] = \varepsilon_{ijk} A_k, \quad [B_i, B_j] = \varepsilon_{ijk} A_k, \quad [A_i, B_j] = \varepsilon_{ijk} B_k$$

9. Show that by making the linear transformation of the generators in Problem 7 to

$$J_i = \frac{1}{2}(A_i + B_i), \quad K_i = \frac{1}{2}(A_i - B_i)$$

the commutators become

$$[J_i, J_j] = \varepsilon_{ijk} J_k, \quad [K_i, K_j] = \varepsilon_{ijk} K_k, \quad [J_i, K_j] = 0$$

This shows that locally $SO(4) = SO(3) \otimes SO(3)$.